

# Instalar Robotics Toolbox

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### 1. Instalar C++ Build Tools

 En caso de no tener las herramientas de de Microsoft visual C++, descargarlas de aqui <u>Visual Studio</u>

 Instalar "Desktop development wit c++"



Ingenierías

# 2. Agregar Msbuild al PATH

#### • Buscar Variables de Sistema



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			Environme	nt Variables	
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• Seleccionar Path y luego edit





## 2. Agregar Msbuild al PATH

• Darle clic a nuevo, y agregar la ruta de a Msbuild normalmente "C:\Program Files\Microsoft Visual Studio\2022\Community\MSBuild\Current\Bin\" Puede variar entre computadoras

%SystemRoot%\system32	New
%SystemRoot%	
%SystemRoot%\System32\Wbem	Edit
%SYSTEMROOT%\System32\WindowsPowerShell\v1.0\	
%SYSTEMROOT%\System32\OpenSSH\	Browse
C:\Program Files (x86)\NVIDIA Corporation\PhysX\Common	
C:\Program Files\NVIDIA Corporation\NVIDIA NvDLISR	Delete
C:\Program Files (x86)\Windows Kits\8.1\Windows Performance Toolkit\	
C:\Program Files\Git\cmd	
C:\Program Files (x86)\Windows Kits\10\Windows Performance Toolkit\	Move Up
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# 3. (Opcional)Configurar Entorno Virtual

- cd /path/to/your/project (Carpeta del Proyecto)
- pip install virtualenv
- python -m venv myenv
- myenv\Scripts\activate



## 4. Instalar el toolbox

• pip3 install roboticstoolbox-python



## 5. Revisar instalacion

• Pip list

